

INSTITUTO SUPERIOR TÉCNICO  
Mestrado em Engenharia Física Tecnológica  
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MATEMÁTICA COMPUTACIONAL

Resolução do Exame e Testes de 21 de Janeiro de 2011

[1]  
(a)<sup>10</sup>

$$x_0 = 0.01234, \quad u_0 = \sin x_0 = x_0 - \frac{x_0^3}{6} + \dots$$

$$\tilde{u}_0 = \text{fl}_c(0.01234 - 0.3132 \times 10^{-6} + \dots) = 0.01233$$

$$z_0 = f(x_0) = x_0 - \sin x_0, \quad \tilde{z}_0 = 0.1000 \times 10^{-4}$$

$$\delta_{\tilde{z}_0} = 1 - \frac{\tilde{z}_0}{z_0} = -30.93$$

(b)<sup>15</sup>

$$u = \sin x, \quad z = f(x) = x - u$$

$$\delta_u^L = \frac{x \cos x}{\sin x} \delta_{\tilde{x}} + \delta_1$$

$$\delta_{\tilde{z}}^L = \frac{x}{z} \delta_{\tilde{x}} - \frac{u}{z} \delta_u^L + \delta_2$$

$$= \frac{x}{z} \delta_{\tilde{x}} - \frac{\sin x}{z} \left( \frac{x \cos x}{\sin x} \delta_{\tilde{x}} + \delta_1 \right) + \delta_2$$

$$= \frac{x}{f(x)} (1 - \cos x) \delta_{\tilde{x}} - \frac{\sin x}{f(x)} \delta_1 + \delta_2$$

$$=: p_f(x) \delta_{\tilde{x}} + q_1(x) \delta_1 + \delta_2$$

O problema é estável para qualquer  $x \in \mathbb{R}$  pois, com  $p_f(0) = \lim_{x \rightarrow 0} p_f(x) = 3$ ,  $p_f(x) \in [0, 3]$  em todo o domínio de  $f$ .

O algoritmo para o cálculo de  $f(x)$  é numericamente instável para  $x \approx 0$  pois  $\lim_{x \rightarrow 0} |q_1(x)| = \infty$ .

[2]  
(a)<sup>10</sup>

$$f : \mathbb{R}^+ \rightarrow \mathbb{R}, \quad f(x) = 2 \ln x + \frac{1}{x} + 1 - x$$

$$f'(x) = \frac{2}{x} - \frac{1}{x^2} - 1 = -\frac{1}{x^2} (x-1)^2$$

$$f''(x) = -\frac{2}{x^2} + \frac{2}{x^3} = \frac{2}{x^3} (1-x)$$

$$\lim_{x \rightarrow 0} f(x) = +\infty, \quad \lim_{x \rightarrow \infty} f(x) = -\infty, \quad f \text{ é decrescente em } \mathbb{R}^+$$

$\Rightarrow f$  tem um único zero em  $\mathbb{R}^+$

(b)<sup>20</sup>  $I = [3.9, 4.1]$

$$f(x) = 0 \Leftrightarrow x = g(x), \quad \forall x > 0$$

$$g(x) = x + f(x) = 2 \ln x + \frac{1}{x} + 1$$

$$g'(x) = \frac{2}{x} - \frac{1}{x^2} = \frac{2}{x^2} \left(x - \frac{1}{2}\right), \quad g'(x) > 0, \quad \forall x \in I$$

$$g''(x) = -\frac{2}{x^2} + \frac{2}{x^3} = \frac{2}{x^3} (1-x), \quad g''(x) < 0, \quad \forall x \in I$$

Condições suficientes de convergência do método do ponto fixo com função iteradora  $g$  para  $z$ ,  $\forall x_0 \in I$ :

(i)  $g \in C^1(I)$

(ii)  $\max_{x \in I} |g'(x)| = g'(3.9) = 0.447074 < 1$ ,

pois  $g'$  é positiva e decrescente em  $I$ .

(iii)  $g(I) \subset I$ ,

pois  $g(3.9) = 3.97836 \in I$ ,  $g(4.1) = 4.06588 \in I$ ,

e  $g$  é crescente em  $I$ .

Método do ponto fixo:

$$x_m = g(x_{m-1}), \quad m \in \mathbb{N}_1, \quad x_0 \in I$$

$$|z - x_m| \leq \frac{L}{1-L} |x_m - x_{m-1}| =: B_m, \quad m \geq 1$$

$$L = \max_{x \in I} |g'(x)| = 0.447074$$

$m$	$x_m$	$B_m$
0	4.0	
1	4.02259	$0.183 \times 10^{-1}$
2	4.03245	$0.797 \times 10^{-2}$

$$z = 4.03245 + \Delta, \quad |\Delta| < B_2$$

[3]

(a)<sup>15</sup>

O método de Jacobi convergirá para a solução do sistema  $Ax = b$  se e só se o raio espectral da matriz iteradora do método for inferior à unidade,  $r_\sigma(C_J) < 1$ .

$$A = D + L + U, \quad M_J = D = 2I, \quad N_J = L + U = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$C_J = -M_J^{-1}N_J = -\frac{1}{2}N$$

$$\det(C_J - \lambda I) = \begin{vmatrix} -\lambda & -\frac{1}{2} & 0 \\ -\frac{1}{2} & -\lambda & -\frac{1}{2} \\ 0 & -\frac{1}{2} & -\lambda \end{vmatrix} = -\lambda \left( \lambda^2 - \frac{1}{2} \right)$$

$$\sigma(C_J) = \left\{ 0, \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}} \right\}$$

$$r_\sigma(C_J) = \frac{1}{\sqrt{2}} < 1$$

(b)<sup>20</sup>

Método de Jacobi:

$$x^{(m+1)} = D^{-1} (b - (L + U)x^{(m)}), \quad m \geq 0$$

Estimativa de erro do método de Jacobi:

$$\|z - x^{(m)}\|_2 \leq \frac{c^m}{1 - c} \|x^{(1)} - x^{(0)}\|_2 < \varepsilon, \quad c = \|C_J\|_2$$

$$m > \frac{\log \frac{(1 - c)\varepsilon}{\|x^{(1)} - x^{(0)}\|_2}}{\log c}$$

$$c = \|C_J\|_2 = \sqrt{r_\sigma(C_J^T C_J)} = \sqrt{r_\sigma(C_J^2)} = r_\sigma(C_J) = \frac{1}{\sqrt{2}}$$

$$x^{(1)} = \frac{1}{2} \left( \begin{bmatrix} 4 \\ 5 \\ 4 \end{bmatrix} - \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right) = \frac{3}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$x^{(1)} - x^{(0)} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \|x^{(1)} - x^{(0)}\|_2 = \frac{\sqrt{3}}{2}$$

$$\varepsilon = 10^{-6} : m > 42.9912$$

$$m = 43$$

[4]<sup>10</sup>

Norma matricial associada à norma da soma em  $\mathbb{R}^n$ :

$$\|A\|_1 = \sup_{x \in \mathbb{R}^n \setminus \{0\}} \frac{\|Ax\|_1}{\|x\|_1}$$

Seja  $x \in \mathbb{R}^n \setminus \{0\}$ . Então:

$$\|Ax\|_1 = \sum_{i=1}^n |(Ax)_i| = \sum_{i=1}^n \left| \sum_{j=1}^n a_{ij} x_j \right| \leq \sum_{j=1}^n |x_j| \sum_{i=1}^n |a_{ij}|$$

$$\text{Seja } c \text{ tal que } c = \max_{1 \leq j \leq n} \sum_{i=1}^n |a_{ij}|$$

$$\text{Então: } \|Ax\|_1 \leq c \|x\|_1, \quad \forall x \in \mathbb{R}^n \setminus \{0\}$$

$$\text{Seja } k \text{ tal que } c = \sum_{i=1}^n |a_{ik}|.$$

$$\text{Seja } y = e_k, \text{ o vector com componentes } y_j = \delta_{jk} = \begin{cases} 1, & j = k \\ 0, & j \neq k \end{cases}.$$

$$\|Ay\|_1 = \sum_{i=1}^n |(Ay)_i| = \sum_{i=1}^n \left| \sum_{j=1}^n a_{ij} \delta_{jk} \right| = \sum_{i=1}^n |a_{ik}| = c = c \|y\|_1$$

Conclui-se pois que  $\|A\|_1 = c$ .

[5]<sup>20</sup>

Método da Newton generalizado:

$$\begin{cases} x^{(m+1)} = x^{(m)} + \Delta x^{(m)} \\ J_f(x^{(m)}) \Delta x^{(m)} = -f(x^{(m)}), \quad m \geq 0 \end{cases}$$

$$J_f(x) = \begin{bmatrix} -6 & 2x_2 & 2x_3 \\ 1 & -5 & 3x_3^2 \\ 2x_1 & -3 & 6 \end{bmatrix}$$

$$x^{(0)} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -6 & 0 & 0 \\ 1 & -5 & 0 \\ 0 & -3 & 6 \end{bmatrix} \Delta x^{(0)} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \Leftrightarrow \Delta x^{(0)} = \begin{bmatrix} 0 \\ 0 \\ \frac{1}{6} \end{bmatrix}$$

$$x^{(1)} = \begin{bmatrix} 0 \\ 0 \\ \frac{1}{6} \end{bmatrix}$$

$$\begin{bmatrix} -6 & 0 & \frac{1}{3} \\ 1 & -5 & \frac{1}{12} \\ 0 & -3 & 6 \end{bmatrix} \Delta x^{(1)} = - \begin{bmatrix} \frac{1}{36} \\ \frac{1}{216} \\ 0 \end{bmatrix} \Leftrightarrow \Delta \tilde{x}^{(1)} = \begin{bmatrix} \frac{359}{76680} \\ \frac{2}{1065} \\ \frac{1}{1065} \end{bmatrix}$$

$$x^{(2)} = \begin{bmatrix} \frac{359}{76680} \\ \frac{2}{1065} \\ \frac{119}{710} \end{bmatrix} = \begin{bmatrix} 0.00468179 \\ 0.00187793 \\ 0.167606 \end{bmatrix}$$

[6]

(a)<sup>20</sup>

Fórmula de Newton às diferenças divididas:

$i$	$x_i$	$f[x_i]$	$f[\cdot, \cdot]$	$f[\cdot, \cdot, \cdot]$	$f[\cdot, \cdot, \cdot, \cdot]$
0	-1.0	-1.0			
1	0.0	0.9093	1.9093		
2	1.0	0.2433	-0.6660	-1.28765	
3	2.0	1.721	1.4777	1.07185	0.7865

$$\begin{aligned}
p_3(x) &= f[x_0] + f[x_0, x_1](x - x_0) + f[x_0, x_1, x_2](x - x_0)(x - x_1) \\
&\quad + f[x_0, x_1, x_2, x_3](x - x_0)(x - x_1)(x - x_2) \\
p_3(x) &= -1.0 + 1.9093(x + 1.0) - 1.28765(x + 1.0)x + 0.7865(x + 1.0)x(x - 1.0) \\
p_3(x) &= 0.9093 - 0.16485x - 1.28765x^2 + 0.7865x^3
\end{aligned}$$

• Alternativa. Fórmula interpoladora de Lagrange:

$$\begin{aligned}
p_3(x) &= \sum_{j=0}^3 f(x_j)l_j(x), \quad l_j(x) = \prod_{i=0, i \neq j}^3 \frac{x - x_i}{x_j - x_i} \\
p_3(x) &= -l_0(x) + 0.9093 l_1(x) + 0.2433 l_2(x) + 1.721 l_3(x) \\
l_0(x) &= \frac{(x - 0.0)(x - 1.0)(x - 2.0)}{(-1.0 - 0.0)(-1.0 - 1.0)(-1.0 - 2.0)} = -\frac{1}{6} x(x - 1.0)(x - 2.0) \\
l_1(x) &= \frac{(x + 1.0)(x - 1.0)(x - 2.0)}{(0.0 + 1.0)(0.0 - 1.0)(0.0 - 2.0)} = \frac{1}{2} (x + 1.0)(x - 1.0)(x - 2.0) \\
l_2(x) &= \frac{(x + 1.0)(x - 0.0)(x - 2.0)}{(1.0 + 1.0)(1.0 - 0.0)(1.0 - 2.0)} = -\frac{1}{2} (x + 1.0)x(x - 2.0) \\
l_3(x) &= \frac{(x + 1.0)(x - 0.0)(x - 1.0)}{(2.0 + 1.0)(2.0 - 0.0)(2.0 - 1.0)} = \frac{1}{6} (x + 1.0)x(x - 1.0)
\end{aligned}$$

$$p_3(x) = 0.9093 - 0.16485x - 1.28765x^2 + 0.7865x^3 \quad \bullet$$

Erro de interpolação:

$$e_3(x) = f(x) - p_3(x) = \frac{f^{(4)}(\xi)}{4!} W_4(x), \quad x \in [-1.0, 2.0]$$

$$W_4(x) = (x + 1)x(x - 1)(x - 2), \quad \xi \in [-1; 2; x] \subset [-1, 2]$$

$$|f(x) - p_3(x)| \leq \frac{1}{24} \max_{x \in [-1, 2]} |f^{(4)}(x)| \max_{x \in [-1, 2]} |W_4(x)|, \quad \forall x \in [-1, 2]$$

$$f(x) = x + \sin(2x + 2), \quad f^{(4)}(x) = 16 \sin(2x + 2)$$

$$\max_{x \in [-1, 2]} |f^{(4)}(x)| = 16$$

$$W_4(x) = x^4 - 2x^3 - x^2 + 2x$$

$$W_4'(x) = 4x^3 - 6x^2 - 2x + 2 = 4(x - z_1)(x - z_2)(x - z_3)$$

$$z_1 = \frac{1 - \sqrt{5}}{2}, \quad z_2 = \frac{1}{2}, \quad z_3 = \frac{1 + \sqrt{5}}{2}$$

$$\max_{x \in [-1, 2]} |W_4(x)| = \max\{|W_4(z_1)|, |W_4(z_2)|, |W_4(z_3)|\} = \max\left\{1, \frac{9}{16}, 1\right\} = 1$$

$$|f(x) - p_3(x)| \leq \frac{16}{24} = \frac{2}{3}, \quad \forall x \in [-1, 2]$$

$$\max_{x \in [-1, 2]} |f(x) - p_3(x)| \leq \frac{2}{3}$$

(b)<sup>15</sup>

Erro de interpolação:

$$e_3(x) = f(x) - q_3(x) = \frac{f^{(4)}(\xi)}{4!} \tilde{W}_4(x), \quad x \in [-1.0, 2.0]$$

$$\tilde{W}_4(x) = \prod_{i=0}^3 (x - x_i), \quad \xi \in [-1; 2; x] \subset [-1, 2]$$

$$\max_{x \in [-1, 2]} |f(x) - q_3(x)| \leq \frac{2}{3} \max_{x \in [-1, 2]} |\tilde{W}_4(x)|$$

Sabe-se que a quantidade

$$\max_{t \in [-1, 1]} \left| \prod_{i=0}^3 (t - t_i) \right|$$

toma o menor valor possível (1/8) quando os nós  $t_0, t_1, t_2, t_3$  são os zeros do polinómio de Chebyshev de grau 4,  $T_4$ . Usando a definição destes polinómios obtemos:

$$T_0(x) = 1, \quad T_1(x) = x, \quad T_2(x) = 2x^2 - 1, \quad T_3(x) = x(4x^2 - 3)$$

$$T_4(x) = 8x^4 - 8x^2 + 1$$

$$\text{Zeros de } T_4 : \quad -t_0 = t_3 = \frac{\sqrt{2 + \sqrt{2}}}{2}, \quad -t_1 = t_2 = \frac{\sqrt{2 - \sqrt{2}}}{2}$$

A quantidade  $\max_{x \in [-1, 2]} |\tilde{W}_4(x)|$  tomará então o menor valor possível (1/8) quando os pontos  $x_0, x_1, x_2, x_3$  forem dados por

$$x_i = X(t_i), \quad i = 0, 1, 2, 3$$

$$X : [-1, 1] \rightarrow [-1, 2], \quad X(t) = -1 + \frac{3}{2}(t + 1)$$

Isto é:

$$x_i = -1 + \frac{3}{2}(t_i + 1), \quad i = 0, 1, 2, 3$$

Resulta então:

$$\max_{x \in [-1, 2]} |f(x) - q_3(x)| \leq \frac{1}{12}$$

[7]<sup>20</sup>

Fórmula dos trapézios composta ( $f \in C([a, b])$ ):

$$I(f) = \int_a^b f(x) dx \approx I_1^{(M)}(f) = \frac{h_M}{2} \left[ f(x_0) + f(x_M) + 2 \sum_{j=1}^{M-1} f(x_j) \right]$$

$$h_M = \frac{b-a}{M}, \quad x_j = a + jh_M, \quad j = 0, 1, \dots, M$$

$$\begin{cases} a = 0, & b = 2, & M = 4, & h_M = \frac{1}{2} \\ x_j = 0.5j, & j = 0, 1, 2, 3, 4 \end{cases}$$

$$I_1^{(4)}(f) = \frac{1}{4} \left[ f(0.0) + f(2.0) + 2(f(0.5) + f(1.0) + f(1.5)) \right] = 4.19385$$

$$\left( I(f) = 4.23653 \right)$$

Erro da fórmula dos trapézios composta:

$$E_1^{(M)}(f) = -\frac{b-a}{12} h_M^2 f''(\xi), \quad \xi \in ]a, b[$$

$$\left| E_1^{(4)}(f) \right| \leq \frac{1}{24} \max_{x \in [0, 2]} |f''(x)|$$

$$f(x) = e^{\sin x}, \quad f'(x) = f(x) \cos x, \quad f''(x) = f(x)(\cos^2 x - \sin x)$$

$$f'''(x) = f(x) \cos x (\cos^2 x - 3 \sin x - 1) = -\frac{1}{2} f(x) \sin(2x)(3 + \sin x)$$

$$f'''(x) = 0 \Leftrightarrow x = 0 \vee x = \frac{\pi}{2}, \quad x \in [0, 2]$$

$$\max_{x \in [0, 2]} |f''(x)| = \max \left\{ |f''(0)|, \left| f''\left(\frac{\pi}{2}\right) \right|, |f''(2)| \right\} = \max\{1, e, 1.82747\} = e$$

$$\left| E_1^{(4)}(f) \right| \leq \frac{e}{24}$$

[8]

(a)<sup>15</sup> Método de Runge-Kutta clássico de 2<sup>a</sup> ordem:

$$y_1 = y_0 + \frac{h}{4} \left[ f(x_0, y_0) + 3f\left(x_0 + \frac{2h}{3}, y_0 + \frac{2h}{3} f(x_0, y_0)\right) \right]$$



$$f(x, y) = x(1 - y^2) - y, \quad x_0 = 1, \quad y_0 = 2$$

$$y_1 = 2 + \frac{h}{4} \left[ f(1, 2) + 3f \left( 1 + \frac{2h}{3}, 2 + \frac{2h}{3} f(1, 2) \right) \right]$$

$$f(1, 2) = -5$$

$$f \left( 1 + \frac{2h}{3}, 2 - \frac{10h}{3} \right) = -5 + \frac{44h}{3} - \frac{20h^2}{9} - \frac{200h^3}{27}$$

$$y_1 = 2 - 5h + 11h^2 - \frac{5h^3}{3} - \frac{50h^4}{9}$$

(b)<sup>15</sup>

$$W'(x) = F(x, W(x))$$

$$W(x) = \begin{bmatrix} y(x) \\ y'(x) \end{bmatrix} = \begin{bmatrix} y(x) \\ z(x) \end{bmatrix}, \quad F(x, W(x)) = \begin{bmatrix} z(x) \\ g(x, y(x), y'(x)) \end{bmatrix}$$

$$g(x, y, z) = x(1 - y^2)z - y$$

Método de Taylor de ordem 2 (passo  $h$ ):

$$W_{n+1} = W_n + hF(x_n, W_n) + \frac{h^2}{2}(D_F F)(x_n, W_n), \quad n \geq 0$$

$$\begin{aligned} (D_F F)(x, W) &= \left( \frac{\partial}{\partial x} + F(x, W) \cdot \nabla_W \right) F(x, W) \\ &= \left( \frac{\partial}{\partial x} + z \frac{\partial}{\partial y} + g(x, y, z) \frac{\partial}{\partial z} \right) \begin{bmatrix} z \\ g(x, y, z) \end{bmatrix} \\ &= \begin{bmatrix} g(x, y, z) \\ g_x(x, y, z) + z g_y(x, y, z) + g(x, y, z) g_z(x, y, z) \end{bmatrix} \\ &= \begin{bmatrix} g(x, y, z) \\ s(x, y, z) \end{bmatrix} \end{aligned}$$

$$s(x, y, z) = (1 - y^2)z + z(-1 - 2xyz) + g(x, y, z)x(1 - y^2)$$

$$\begin{bmatrix} y_{n+1} \\ z_{n+1} \end{bmatrix} = \begin{bmatrix} y_n \\ z_n \end{bmatrix} + h \begin{bmatrix} z_n \\ g(x_n, y_n, z_n) \end{bmatrix} + \frac{h^2}{2} \begin{bmatrix} g(x_n, y_n, z_n) \\ s(x_n, y_n, z_n) \end{bmatrix}$$

$$y_1 = y_0 + h z_0 + \frac{h^2}{2} g(x_0, y_0, z_0) = 2 + 2h - 4h^2$$

$$z_1 = z_0 + h g(x_0, y_0, z_0) + \frac{h^2}{2} s(x_0, y_0, z_0) = 2 - 8h$$