

INSTITUTO SUPERIOR TÉCNICO
Mestrado em Engenharia Física Tecnológica
Ano Lectivo: 2010/2011 Semestre: 1^o

MATEMÁTICA COMPUTACIONAL

Formulário – I

1. Representação de Números e Teoria de Erros

Erro, erro absoluto, erro relativo ($\tilde{x} \approx x$):

$$\begin{aligned} \text{(i)} \quad x \in \mathbb{R} : \quad e_{\tilde{x}} &= x - \tilde{x}, & |e_{\tilde{x}}|, & \quad \delta_{\tilde{x}} = \frac{e_{\tilde{x}}}{x}, & \quad |\delta_{\tilde{x}}| \quad (x \neq 0) \\ \text{(ii)} \quad x \in \mathbb{R}^n : \quad e_{\tilde{x}} &= x - \tilde{x}, & \|e_{\tilde{x}}\|, & \quad \delta_{\tilde{x}} = \frac{e_{\tilde{x}}}{\|x\|}, & \quad \|\delta_{\tilde{x}}\| \quad (x \neq 0) \end{aligned}$$

Representação de números reais (notação científica):

$$\begin{aligned} x &= \sigma m \beta^t \in \mathbb{R} \setminus \{0\} \\ \text{(base)} \quad \beta &\in \mathbb{N} \setminus \{1\}, & \text{(sinal)} \quad \sigma &\in \{+, -\}, & \text{(expoente)} \quad t &\in \mathbb{Z} \\ \text{(mantissa)} \quad m &= (0.a_1a_2\dots)_\beta \in [\beta^{-1}, 1[, & a_i &\in \{0, 1, \dots, \beta - 1\}, & a_1 &\neq 0 \end{aligned}$$

Sistema de ponto flutuante:

$$\begin{aligned} \text{FP}(\beta, n, t^-, t^+) &= \{x \in \mathbb{Q} : x = \sigma m \beta^t\} \cup \{0\} \\ \beta &\in \mathbb{N} \setminus \{1\}, & \sigma &\in \{+, -\}, & t^- \leq t \leq t^+, & t, t^-, t^+ \in \mathbb{Z} \\ m &= (0.a_1a_2\dots a_n)_\beta \in [\beta^{-1}, 1 - \beta^{-n}], & a_i &\in \{0, 1, \dots, \beta - 1\}, & a_1 &\neq 0 \end{aligned}$$

Arredondamentos:

$$x = \sigma(0.a_1a_2\dots a_n a_{n+1}\dots)_\beta \times \beta^t \in \mathbb{R}, \quad \text{fl}(x) \in \text{FP}(\beta, n, t^-, t^+)$$

(i) arredondamento por corte:

$$\text{fl}_c(x) = \sigma(0.a_1a_2\dots a_n)_\beta \times \beta^t$$

(ii) arredondamento simétrico (β par):

$$\text{fl}_s(x) = \begin{cases} \sigma(0.a_1a_2\dots a_n)_\beta \times \beta^t, & 0 \leq a_{n+1} < \frac{\beta}{2} \\ \sigma[(0.a_1a_2\dots a_n)_\beta + \beta^{-n}] \times \beta^t, & \frac{\beta}{2} \leq a_{n+1} < \beta \end{cases}$$

Erros de arredondamento ($x = \sigma m \beta^t \in \mathbb{R}$, $\tilde{x} = \text{fl}(x) \in \text{FP}(\beta, n, t^-, t^+)$):

(i) arredondamento por corte:

$$|e_{\tilde{x}}| \leq \beta^{t-n}, \quad |\delta_{\tilde{x}}| \leq \beta^{1-n} =: u_c$$

(ii) arredondamento simétrico:

$$|e_{\tilde{x}}| \leq \frac{1}{2} \beta^{t-n}, \quad |\delta_{\tilde{x}}| \leq \frac{1}{2} \beta^{1-n} =: u_s$$

(u_c, u_s : unidade de arredondamento do sistema $\text{FP}(\beta, n, t^-, t^+)$)

Operações aritméticas num sistema de ponto flutuante ($x, y \in \mathbb{R}$; $\circ = +, -, \times, \div$):

$$x \square y = \text{fl}(\text{fl}(x) \circ \text{fl}(y))$$

Propagação de erros ($x = (x_1, \dots, x_n) \in \mathbb{R}^n$, $\phi: \mathbb{R}^n \rightarrow \mathbb{R}$, $\tilde{x} \approx x$, $\tilde{\phi} = \text{fl} \circ \phi$):

$$\begin{aligned} e_{\phi(\tilde{x})} &= \phi(x) - \phi(\tilde{x}) \approx e_{\phi(\tilde{x})}^L = \sum_{k=1}^n \frac{\partial \phi}{\partial x_k}(x) e_{\tilde{x}_k} \\ \delta_{\phi(\tilde{x})} &= \frac{e_{\phi(\tilde{x})}}{\phi(x)} \approx \delta_{\phi(\tilde{x})}^L = \sum_{k=1}^n p_{\phi, x_k}(x) \delta_{\tilde{x}_k}, \quad p_{\phi, x_k}(x) = \frac{x_k \frac{\partial \phi}{\partial x_k}(x)}{\phi(x)} \\ \delta_{\tilde{\phi}(\tilde{x})} &= \frac{\phi(x) - \tilde{\phi}(\tilde{x})}{\phi(x)} \approx \delta_{\phi(\tilde{x})}^L + \delta_{\text{arr}}, \quad \delta_{\phi(\tilde{x})}^L = \sum_{k=1}^n p_{\phi, x_k} \delta_{\tilde{x}_k}, \quad \delta_{\text{arr}} = \sum_{k=1}^m q_k \delta_{\text{arr}_k} \end{aligned}$$

2. Métodos Iterativos

Normas vectoriais ($x = (x_1, \dots, x_n) \in \mathbb{R}^n$):

$$\begin{aligned} \|x\|_1 &= \sum_{i=1}^n |x_i|, & \|x\|_2 &= \sqrt{\sum_{i=1}^n |x_i|^2}, & \|x\|_\infty &= \max_{1 \leq i \leq n} |x_i| \\ \text{(norma da soma)} & & \text{(norma Euclidiana)} & & \text{(norma do máximo)} \end{aligned}$$

Coefficiente assintótico de convergência de ordem $r \geq 1$ de sucessão $\{x_m\}$, $x_m \rightarrow x$:

$$K_\infty^{[r]} = \lim_{m \rightarrow \infty} \frac{\|x - x_{m+1}\|}{\|x - x_m\|^r}$$

3. Resolução de Equações Não-lineares ($f : \mathbb{R} \rightarrow \mathbb{R}$)

Método da bissecção ($f(z) = 0$, $f \in C([a, b])$, $f(a)f(b) < 0$):

$$x_{m+1} = x_m + \frac{b-a}{2^{m+2}} \operatorname{sgn}[f(a)f(x_m)], \quad m = 0, 1, \dots, \quad x_0 = \frac{a+b}{2}$$

$$|z - x_m| \leq \frac{b-a}{2^{m+1}}, \quad |z - x_{m+1}| \leq |x_{m+1} - x_m|$$

Método do ponto fixo ($f(z) = 0 \Leftrightarrow z = g(z)$):

$$(|g(x) - g(y)| \leq L|x - y|, \quad \forall x, y \in I \subset \mathbb{R}, \quad L < 1; \quad g(I) \subset I)$$

$$x_{m+1} = g(x_m), \quad m = 0, 1, \dots$$

$$|z - x_{m+1}| \leq L|z - x_m|, \quad |z - x_m| \leq L^m|z - x_0|$$

$$|z - x_m| \leq \frac{1}{1-L}|x_{m+1} - x_m|, \quad |z - x_{m+1}| \leq \frac{L}{1-L}|x_{m+1} - x_m|$$

$$|z - x_m| \leq \frac{L^m}{1-L}|x_1 - x_0|$$

o • $g'(z) \neq 0$, $g \in C^1(I)$, $L = \max_{x \in I} |g'(x)| < 1$:

$$z - x_{m+1} = g'(\xi_m)(z - x_m), \quad \xi_m \in]z; x_m[$$

$$|z - x_{m+1}| \leq L|z - x_m|, \quad |z - x_m| \leq L^m|z - x_0|$$

$$\lim_{m \rightarrow \infty} \frac{z - x_{m+1}}{z - x_m} = g'(z), \quad K_\infty^{[1]} = |g'(z)|$$

o • $g^{(r)}(z) = 0$, $r = 1, \dots, p-1$, $g^{(p)}(z) \neq 0$, $p = 2, 3, \dots$, $g \in C^p(I)$

$$z - x_{m+1} = \frac{1}{p!}(-1)^{p+1}g^{(p)}(\xi_m)(z - x_m)^p, \quad \xi_m \in]z; x_m[$$

$$|z - x_{m+1}| \leq K_p|x - x_m|^p, \quad |z - x_m| \leq K_p^{\frac{1}{1-p}} \left(K_p^{\frac{1}{p-1}}|z - x_0| \right)^{p^m}$$

$$K_p = \frac{1}{p!} \max_{x \in I} |g^{(p)}(x)|$$

$$\lim_{m \rightarrow \infty} \frac{z - x_{m+1}}{(z - x_m)^p} = \frac{(-1)^{p+1}}{p!} g^{(p)}(z), \quad K_\infty^{[p]} = \frac{1}{p!} |g^{(p)}(z)|$$

Método de Newton ($f(z) = 0$, $f'(z) \neq 0$, $f \in C^2(I)$):

$$x_{m+1} = x_m - \frac{f(x_m)}{f'(x_m)}, \quad m = 0, 1, \dots$$

$$z - x_{m+1} = -\frac{f''(\xi_m)}{2f'(x_m)}(z - x_m)^2, \quad \xi_m \in]z; x_m[$$

$$|z - x_{m+1}| \leq K|z - x_m|^2, \quad |z - x_m| \leq \frac{1}{K} (K|z - x_0|)^{2^m}$$

$$K = \frac{\max_{x \in I} |f''(x)|}{2 \min_{x \in I} |f'(x)|}$$

$$\lim_{m \rightarrow \infty} \frac{z - x_{m+1}}{(z - x_m)^2} = -\frac{f''(z)}{2f'(z)}, \quad K_\infty^{[2]} = \left| \frac{f''(z)}{2f'(z)} \right|$$

○ • $f^{(r)}(z) = 0, r = 2, \dots, p-1, f^{(p)}(z) \neq 0, p = 3, 4, \dots, f \in C^{p+1}(I)$

$$\lim_{m \rightarrow \infty} \frac{z - x_{m+1}}{(z - x_m)^p} = \frac{(-1)^{p+1}(p-1)}{p!} \frac{f^{(p)}(z)}{f'(z)}, \quad K_\infty^{[p]} = \frac{p-1}{p!} \left| \frac{f^{(p)}(z)}{f'(z)} \right|$$

Método da secante ($f(z) = 0, f'(z) \neq 0, f \in C^2(I)$):

$$x_{m+1} = x_m - f(x_m) \frac{x_m - x_{m-1}}{f(x_m) - f(x_{m-1})}, \quad m = 1, 2, \dots$$

$$z - x_{m+1} = -\frac{f''(\eta_m)}{2f'(\xi_m)} (z - x_m)(z - x_{m-1}), \quad \xi_m, \eta_m \in]x_{m-1}; z; x_m[$$

$$|z - x_{m+1}| \leq K |z - x_m| |z - x_{m-1}|, \quad |z - x_m| \leq \frac{1}{K} \delta^{q_m}$$

$$K = \frac{\max_{x \in I} |f''(x)|}{2 \min_{x \in I} |f'(x)|}, \quad \delta = \max\{K|z - x_0|, K|z - x_1|\}, \quad q_m : \text{sucessão de Fibonacci}$$

$$\lim_{m \rightarrow \infty} \frac{|z - x_{m+1}|}{|z - x_m|^r} = \left| \frac{f''(z)}{2f'(z)} \right|^{r-1} =: K_\infty^{[r]}, \quad r = \frac{\sqrt{5} + 1}{2}$$

4. Resolução de Sistemas Lineares ($Ax = b, A \in \mathbb{M}^n(\mathbb{R}), b, x \in \mathbb{R}^n$)

Normas matriciais induzidas por normas vectoriais ($A = [a_{ij}] \in \mathbb{M}^n(\mathbb{R})$):

$$\|A\|_p = \sup_{x \in \mathbb{R}^n \setminus \{0\}} \frac{\|Ax\|_p}{\|x\|_p}, \quad p = 1, 2, \infty$$

$$\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^n |a_{ij}|, \quad \|A\|_2 = \sqrt{r_\sigma(A^*A)}, \quad \|A\|_\infty = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|$$

(norma por colunas) (norma Euclidiana) (norma por linhas)

$$r_\sigma(A) = \max_{\lambda \in \sigma(A)} |\lambda|, \quad \sigma(A) : \text{espectro de } A$$

Número de condição de uma matriz:

$$\text{cond}_p(A) = \|A\|_p \|A^{-1}\|_p, \quad p = 1, 2, \infty, \quad \text{cond}_*(A) = r_\sigma(A)r_\sigma(A^{-1})$$

Condicionamento de sistemas lineares ($Ax = b$, $\tilde{A}\tilde{x} = \tilde{b}$):

$$\frac{\|x - \tilde{x}\|_p}{\|x\|_p} \leq \frac{\text{cond}_p(A)}{1 - \frac{\|A - \tilde{A}\|_p}{\|A\|_p} \text{cond}_p(A)} \left(\frac{\|A - \tilde{A}\|_p}{\|A\|_p} + \frac{\|b - \tilde{b}\|_p}{\|b\|_p} \right)$$

$$\frac{\|A - \tilde{A}\|_p}{\|A\|_p} \text{cond}_p(A) = \|A - \tilde{A}\|_p \|A^{-1}\|_p < 1, \quad p = 1, 2, \infty$$

Métodos iterativos:

$$Mx^{(k+1)} = -Nx^{(k)} + b, \quad k = 0, 1, \dots$$

$$M + N = A = L + D + U$$

$$x^{(k+1)} = Cx^{(k)} + w, \quad k = 0, 1, \dots$$

$$C = -M^{-1}N = I - M^{-1}A, \quad w = M^{-1}b$$

$$\|x - x^{(k+1)}\| \leq c\|x - x^{(k)}\|, \quad \|x - x^{(k)}\| \leq c^k\|x - x^{(0)}\|$$

$$\|x - x^{(k)}\| \leq \frac{1}{1-c}\|x^{(k+1)} - x^{(k)}\|, \quad \|x - x^{(k+1)}\| \leq \frac{c}{1-c}\|x^{(k+1)} - x^{(k)}\|$$

$$\|x - x^{(k)}\| \leq \frac{c^k}{1-c}\|x^{(1)} - x^{(0)}\|, \quad (c = \|C\| < 1)$$

- Método de Jacobi ($M = D$):

$$x^{(k+1)} = D^{-1} [b - (L + U)x^{(k)}], \quad k = 0, 1, \dots$$

- Método de Gauss-Seidel ($M = D + L$):

$$x^{(k+1)} = D^{-1} (b - Lx^{(k+1)} - Ux^{(k)}), \quad k = 0, 1, \dots$$

- Método de Jacobi modificado $\left(M = \frac{D}{\omega}, \omega \in \mathbb{R} \setminus \{0\} \right)$:

$$x^{(k+1)} = (1 - \omega)x^{(k)} + \omega D^{-1} [b - (L + U)x^{(k)}], \quad k = 0, 1, \dots$$

- Método de Gauss-Seidel modificado ou SOR $\left(M = \frac{D}{\omega} + L, \omega \in \mathbb{R} \setminus \{0\} \right)$:

$$x^{(k+1)} = (1 - \omega)x^{(k)} + \omega D^{-1} (b - Lx^{(k+1)} - Ux^{(k)}), \quad k = 0, 1, \dots$$